



Intelligence Goals in AI Relations AI Today AI in Robotic

This Course

Agents and Environments

### What Is AI?

School of Computing and Data Science

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- Intelligence Goals in AI
- Relations AI Today
- This Course

Agents and Environments

## What Is Intelligence?

What behaviors require intelligence? What makes an agent intelligent?



# **Goals in AI**

#### What Is AI?

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Agents and Environments Cognitive Modeling: human-like behavior Engineering: human-like performance Rational: perfect/optimal behavior Bounded-rational: behaving as close to perfect as possible

Subfields: knowledge representation and reasoning, computer problem-solving, planning, machine learning, natural language processing, (autonomous) robotics, intelligent agents, multi-agent systems, distributed AI, intelligent user interfaces, machine vision



### Relations

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- CS: algorithms
- Engineering: applications
- Cognitive psych: modeling
- Math: logic, statistics
- Linguistics: language processing
- Operations research: optimization
- Economics: agents, incentives



# AI Today

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- Games: chess, backgammon, Jeopardy!, crosswords, go, StarCraft II, Gran Turismo
- Design: VLSI, jet engines
- Diagnosis: loans, customer service, medical testing and classification
- Planning: airports, flight routes, logistics
- Learning: Amazon, Netflix, Walmart, Facebook
- Robotics: ping-pong, driving, flying, swimming
- Language: voice recognition, translation, subtitles
- Vision: scene descriptions, face recognition
- Creativity: writing, art



### **AI in Robotics**

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#### This Course

Schedule

Formalisms

Agents and Environments

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### Schedule

- Schedule Formalisms
- Agents and Environments
- **1** Problem solving: sampling robot planner
- 2 Logic: theorem prover
- **3** Planning: general planner
- 4 Learning: reinforcement learner, handwriting classifier
- 5 Probabilistic reasoning



#### Formalisms Agents and Environments

### **Formalisms**

- 1 combinatorial search
- 2 propositional logic
- 3 first-order logic
- 4 Markov decision processes
- 5 hidden Markov models
- 6 Bayesian networks

Missing: NLP, vision, robotics, cognition, neural nets



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#### Agents and Environments

Agent Designs Examples Environments Search Space

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### **Agent Designs**

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Agent Designs

Environments Search Space Reflex: sensors  $\rightarrow$  actuators

Reflex with state: sensors + state  $\rightarrow$  actuators + new state Goal-based: reason to achieve goals

Utility-based: quantitative measure of achievement



This Course

Agents and Environments

Agent Designs

Examples

Environments

#### 1 Thermostat

**2** DART logistics planner

3 Mail delivery bot

**Examples of Agents** 

- 4 Medical diagnosis system
- 5 Eliza



#### Environments

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Agents and Environments

Agent Designs Examples

Environments

Observability: complete, partial, hidden Predictability: deterministic, strategic, stochastic Interaction: one-off, sequential Time: static, dynamic State: discrete, continuous Agents: single, multiagent (competitive, cooperative)



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Agent Designs

Examples

Search Space

### **Example Search Space**